ICS95V157

RENESAS

2.5V Single-Ended to SSTL_2 Clock Driver (45MHz - 233MHz)

Recommended Application:

Single-ended clock input with zero delay board fan out

Product Description/Features:

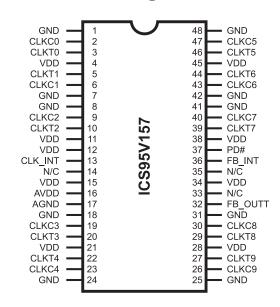
- Low skew, low jitter PLL clock driver
- 1 to 10 differential clock distribution (SSTL_2)
- Feedback pin for input to output synchronization
- PD# for power management
- Spread Spectrum tolerant inputs

Switching Characteristics:

- CYCLE CYCLE jitter: <60ps
- OUTPUT OUTPUT skew: <60ps
- Period jitter: ±30ps
- DUTY CYCLE: 49.5% 50.5%

Block Diagram FB_OUTT CLKT0 CLKC0 CLKT1 CLKC1 Control CLKT2 PD# CLKC2 Logic I **CLKT3** CLKC3 CLKT4 CLKC4 FB_INT CLKT5 CLKC5 т PLL CLKT6 I CLK_INT -CLKC6 1 CLKT7 т CLKC7 CLKT8 CLKC8 CLKT9 CLKC9

Pin Configuration



48-Pin TSSOP

6.10 mm. Body, 0.50 mm. pitch = TSSOP

Functionality

	INPUTS			OUTP	PLL State	
AVDD	PD#	CLK_INT	CLKT	CLKC	FB_OUTT	FLL State
GND	Н	L	L	Н	L	Bypassed/off
GND	Н	Н	Н	L	Н	Bypassed/off
2.5V (nom)	L	L	z	Z	Z	off
2.5V (nom)	L	Н	z	Z	Z	off
2.5V (nom)	Н	L	L	Н	L	on
2.5V (nom)	Н	Н	н	L	Н	on

Pin Descriptions

PIN NUMBER	PIN NAME	TYPE	DESCRIPTION		
4, 11, 12, 15, 21, 28, 34, 38, 45,	VDD	PWR	Power supply, 2.5V		
1, 7, 8, 18, 24, 25, 31, 41, 42, 48	GND	PWR	Ground		
16	AVDD	PWR	Analog power supply, 2.5V		
17	AGND	PWR	Analog ground		
27, 29, 39, 44, 46, 22, 20, 10, 5, 3	CLKT[9:0]	OUT	"True" Clock of differential pair outputs		
26, 30, 40, 43, 47, 23, 19, 9, 6, 2	CLKC[9:0]	OUT	"Complementary" clocks of differential pair outputs		
13	CLK_INT	IN	"True" reference clock input		
32	FB_OUTT	OUT	"True" " Feedback output, dedicated for external feedback. It switches at the same frequency as the CLK. This output must be wired to FB_INT		
36	FB_INT	IN	"True" Feedback input, provides feedback signal to the internal PLL for synchronization with CLK_INT to eliminate phase error		
14, 33, 35	N/C	-	Not connected		
37	PD#	IN	Power Down. LVCMOS input		

This PLL Clock Buffer is designed for a V_{DD} of 2.5V, an AV_{DD} of 2.5V and differential data input and output levels.

ICS95V157 is a zero delay buffer that distributes a single-ended clock input (CLK_INT) to ten differential pair of clock outputs (CLKT[0:9], CLKC[0:9]) and one single-ended feedback clock output (FB_OUTT). The clock outputs are controlled by the input clocks (CLK_INT), the feedback clock (FB_INT), the 2.5-V LVCMOS input (PD#) and the analog power input (AV_{DD}). When input (PD#) is low while power is applied, the receivers are disabled, the PLL is turned off and the differential clock outputs are tri-stated. When AV_{DD} is grounded, the PLL is turned off and bypassed for test purposes.

The PLL in the **ICS95V157** clock driver uses the input clocks (CLK_INT) and the feedback clock (FB_INT) to provide high-performance, low-skew, low-jitter, output differential clocks (CLKT [0:9], CLKC [0:9]). **ICS95V157** is also able to track Spread Spectrum Clock (SSC) for reduced EMI.

ICS95V157 is characterized for operation from 0°C to 85°C.

⁰⁵⁰¹C-11/24/08

Absolute Maximum Ratings

Supply Voltage (VDD & AVDD)	-0.5V to 4.6V
Logic Inputs	GND -0.5 V to V _{DD} + 0.5 V
Ambient Operating Temperature	0°C to +85°C
Storage Temperature	–65°C to +150°C

Stresses above those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These ratings are stress specifications only and functional operation of the device at these or any other conditions above those listed in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect product reliability.

$I_A = 0 - 85^{\circ}C$; Supply Voltage A _{VDD} , $V_{DD} = 2.5 V + - 0.2V$ (unless otherwise stated)							
PARAMETER SYMBOL		CONDITIONS	MIN	TYP	MAX	UNITS	
Input High Current	I _{IH}	$V_{I} = V_{DD}$ or GND	5			μA	
Input Low Current	I	$V_{I} = V_{DD}$ or GND			5	μA	
Operating Supply	I _{DD2.5}	C _L = 0pf @ 200MHz			148	mA	
Current	I _{DDPD}	$C_{L} = 0 p f$			100	μA	
High Impedance Output Current	I _{OZ}	$V_{DD} = 2.7V$, Vout = V_{DD} or GND			±10	mA	
Input Clamp Voltage	V _{IK}	V _{DD} = 2.3V lin = -18mA			-1.2	V	
High-level output	V	I _{OH} = -1 mA	V _{DD} - 0.1			V	
voltage	V _{OH}	I _{OH} = -12 mA	1.7V			V	
	N	I _{OL} =1 mA			0.1	V	
Low-level output voltage	V _{OL}	I _{OH} =12 mA			0.6	V	
Input Capacitance ¹	C _{IN}	$V_{I} = GND \text{ or } V_{DD}$	2.5		3.5	pF	

Electrical Characteristics - Input/Supply/Common Output Parameters T = 0.95% Supply Voltage A = $V_{12} = 2.5 V_{12} V_{12} = 0.25 V_{12}$ (uplose otherwise stated)

¹Guaranteed by design at 233MHz, not 100% tested in production.

Recommended Operating Condition (see note1)

 $T_A = 0 - 85^{\circ}C$; Supply Voltage AVDD, VDD = 2.5 V +/- 0.2V (unless otherwise stated)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Supply Voltage	V_{DD}, A_{VDD}		2.3	2.5	2.7	V
Low level input voltage	V _{IL}	CLK_INT, FB_INT		0.4	V _{DD} /2 - 0.18	V
Low level input voltage	۷IL	PD#	-0.3		0.7	V
High level input voltage	V _{IH}	CLK_INT, FB_INT	$V_{DD}/2 + 0.18$	2.1		V
nigit level input voltage	VIH	PD#	1.7		V _{DD} + 0.6	V
DC input signal voltage (note 2)	V _{IN}		-0.3		V _{DD} + 0.3	V
Output differential cross- voltage (note 4)	V _{ox}		V _{DD} /2 - 0.15		V _{DD} /2 + 0.15	V
High level output current	I _{OH}				-6.4	mA
Low level output current	I _{OL}				5.5	mA
Operating free-air temperature	T _A		0		85	°C

Notes:

- 1. Unused inputs must be held high or low to prevent them from floating.
- 2. DC input signal voltage specifies the allowable DC execution of differential input.
- 3. Differential inputs signal voltages specifies the differential voltage [VTR-VCP] required for switching, where VT is the true input level and VCP is the complementary input level.
- 4. Differential cross-point voltage is expected to track variations of V_{DD} and is the voltage at which the differential signal must be crossing.

Timing Requirements

 $T_A = 0 - 85^{\circ}C$; Supply Voltage A_{VDD}, $V_{DD} = 2.5 V + - 0.2V$ (unless otherwise stated)

PARAMETER	SYMBOL	CONDITIONS	MIN	MAX	UNITS
Max clock frequency	freq _{op}	2.5V <u>+</u> 0.2V @ 25⁰C	45	233	MHz
Application Frequency Range	freq _{App}	2.5V <u>+</u> 0.2V @ 25°C	95	210	MHz
Input clock duty cycle	d _{tin}		40	60	%
CLK stabilization	T _{STAB}			15	μs

Switching Characteristics (see note 3)

PARAMETER	SYMBOL	CONDITION	MIN	TYP	MAX	UNITS
Low-to high level	t _{PLH} 1	CLK_IN to any output		5.5		ns
propagation delay time	٩PLH	CER_IN to any output		5.5		115
High-to low level propagation	+ 1	CLK_IN to any output		5.5		ns
delay time	t _{PLL} ¹	CER_IN to any output		5.5		115
Output enable time	t _{EN}	PD# to any output		5		ns
Output disable time	tdis	PD# to any output		5		ns
Period jitter	T _{jit (per)}	100MHz to 200MHz	-30		30	ps
Half-period jitter	t(jit_hper)	100MHz to 200MHz	-75		30	ps
Input clock slew rate	t _{sl(i)}		1		4	V/ns
Output clock slew rate	t _{sl(o)}		1		2.5	V/ns
Cycle to Cycle Jitter ¹	T_{cyc} - T_{cyc}	100MHz to 200MHz			60	ps
Phase error	t _(phase error) 4		-50	0	50	ps
Output to Output Skew	T _{skew}				60	ps

Notes:

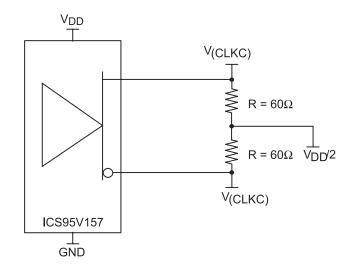
1. Refers to transition on noninverting output in PLL bypass mode.

2. While the pulse skew is almost constant over frequency, the duty cycle error increases at higher frequencies. This is due to the formula: duty cycle= t_{wH}/t_c , where the cycle (t_c) decreases as the frequency goes up.

3. Switching characteristics guaranteed for application frequency range.

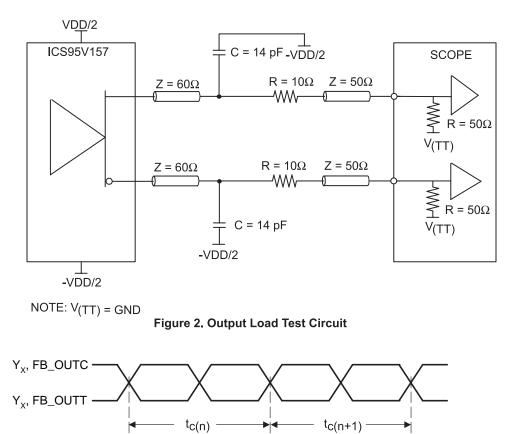
4. Static phase offset shifted by design.

⁰⁵⁰¹C-11/24/08



Parameter Measurement Information

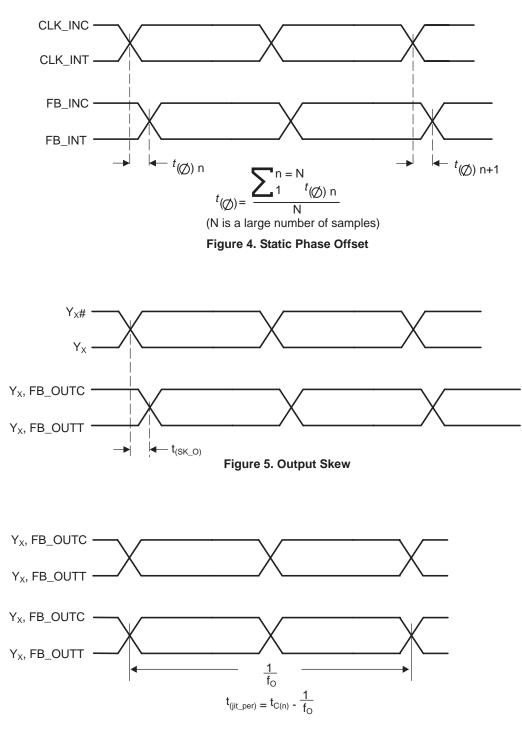




 $t_{jit(cc)} = t_{c(n)} \pm t_{c(n+1)}$

Figure 3. Cycle-to-Cycle Jitter





Parameter Measurement Information

Figure 6. Period Jitter



Parameter Measurement Information

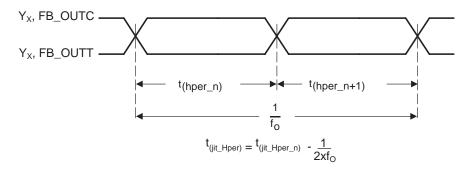


Figure 7. Half-Period Jitter

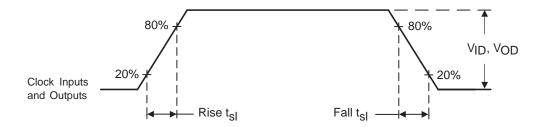
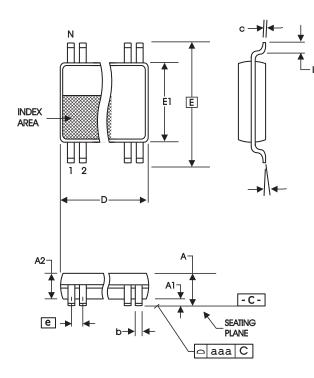


Figure 8. Input and Output Slew Rates



	In Millin		In Inches		
SYMBOL	COMMON DI	MENSIONS	COMMON DIMENSIONS		
	MIN	MAX	MIN	MAX	
A		1.20		.047	
A1	0.05	0.15	.002	.006	
A2	0.80	1.05	.032	.041	
b	0.17	0.27	.007	.011	
С	0.09	0.20	.0035	.008	
D	SEE VARIATIONS		SEE VARIATIONS		
E	8.10 B	ASIC	0.319 BASIC		
E1	6.00	6.20	.236	.244	
е	0.50 B	ASIC	0.020 BASIC		
L	0.45	0.75	.018	.030	
Ν	SEE VARIATIONS		SEE VARIATIONS		
α	0°	8°	0°	8°	
aaa		0.10		.004	

VARIATIONS

Ν	D m	m.	D (inch)		
	MIN	MAX	MIN	MAX	
48	12.40	12.60	.488	.496	

Reference Doc.: JEDEC Publication 95, M O-153

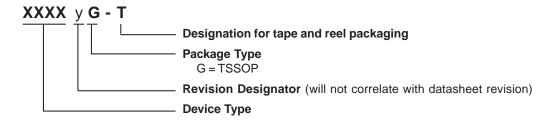
10-0039

6.10 mm. Body, 0.50 mm. pitch TSSOP (240 mil) (20 mil)

Ordering Information

95V157⊻G - T

Example:



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