

#### **Model Number**

#### UB2000-30GM-E5-V15

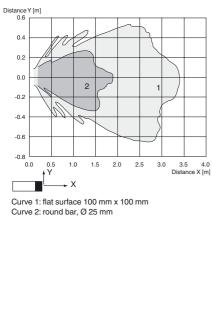
Single head system

#### **Features**

- Switch output
- 5 different output functions can be set
- . **Program input**
- Synchronization options
- **Deactivation option** •
- . **Temperature compensation**
- Insensitive to compressed air

#### Diagrams

## Characteristic response curve



**Technical data General specifications** Sensing range Adjustment range Dead band Standard target plate Transducer frequency Response delay Indicators/operating means LED green

LED yellow

LED red

**Electrical specifications** Operating voltage U<sub>B</sub> No-load supply current Io Input/Output Synchronization

Synchronization frequency Common mode operation Multiplex operation

Input Input type

#### Output

Output type Rated operating current Ie Voltage drop U<sub>d</sub> Repeat accuracy Switching frequency f Range hysteresis H Temperature influence Ambient conditions Ambient temperature Storage temperature Mechanical specifications Connection type Degree of protection Material

Housing Transduce Mass

**Factory settings** Output

Compliance with standards and directives

Standard conformity Standards

## Approvals and certificates

EAC conformity UL approval CSA approval CCC approval

80 ... 2000 mm 120 ... 2000 mm 0 ... 80 mm 100 mm x 100 mm approx. 180 kHz approx. 150 ms

solid: Power-on flashing: program function object detected solid: switching state switch output flashing: program function normal operation: "fault" program function: no object detected

10 ... 30 V DC , ripple 10 %SS ≤ 50 mA

bi-directional 0 level -U<sub>B</sub>...+1 V 1 level: +4 V...+U<sub>B</sub> input impedance: > 12 KOhm synchronization pulse:  $\geq$  100 µs, synchronization interpulse period: ≥ 2 ms

< 30 Hz  $\leq 30~Hz$  / n , n = number of sensors , n  $\leq 5$ 

1 program input, operating range 1: -U<sub>B</sub> ... +1 V, operating range 2: +4 V ... +Ü<sub>B</sub> input impedance: > 4.7 k $\Omega$ ; program pulse: ≥ 1 s

1 switch output PNP, Normally open/closed, programmable 200 mA , short-circuit/overload protected ≤ 2.5 V  $\leq 0.5~$  % of switching point  $\leq$  3.3 Hz 1 % of the set operating distance < 2 % of far switch point

-25 ... 70 °C (-13 ... 158 °F) -40 ... 85 °C (-40 ... 185 °F)

Connector plug M12 x 1 , 5-pin IP65

nickel plated brass; plastic components: PBT epoxy resin/hollow glass sphere mixture; polyurethane foat 140 g

Switch point A1: 220 mm Switch point A2: 2100 mm output function: Window mode output behavior: NO contact

EN 60947-5-2:2007+A1:2012 IEC 60947-5-2:2007 + A1:2012

TR CU 020/2011 cULus Listed, General Purpose cCSAus Listed, General Purpose CCC approval / marking not required for products rated ≤36 V

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Refer to "General Notes Relating to Pepperl+Fuchs Product Information"

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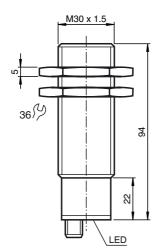
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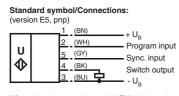
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# Dimensions



# **Electrical Connection**



Wire colors in accordance with EN 60947-5-2.

## **Pinout**

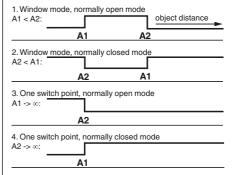


Wire colors in accordance with EN 60947-5-2

1	BN	(brown)
2	WH	(white)
3	BU	(blue)
4	BK	(black)
5	GY	(gray)

# Additional Information

# Programmable output modes



5. A1 -> ∞, A2 -> ∞: Object presence detection mode Object detected: Switch output closed No object detected: Switch output open

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## Accessories

#### BF 30

Mounting flange, 30 mm

## BF 30-F

Plastic mounting adapter, 30 mm

## BF 5-30

Universal mounting bracket for cylindrical sensors with a diameter of 5 ... 30 mm

#### UVW90-M30

Ultrasonic -deflector

## UVW90-K30

Ultrasonic -deflector

#### UB-PROG2 Programming unit

V15-G-2M-PVC

Female cordset, M12, 5-pin, PVC cable

# **Description of Sensor Functions**

## Programming procedure

The sensor features a programmable switch output with two programmable switch points. Programming the switch points and the operating mode is done by applying the supply voltage  $-U_B$  or  $+U_B$  to the Teach-In input. The supply voltage must be applied to the Teach-In input for at least 1 s. LEDs indicate whether the sensor has recognized the target during the programming procedure.

#### Note:

If a programming adapter UB-PROG2 is used for the programming procedure, button A1 is assigned to -U<sub>B</sub> and button A2 is assigned to +U<sub>B</sub>.

## Programming of the switch output

## Window Modes

## Normally open (NO) output

- 1. Place the target at the near end of the desired switch window
- 2. Program the window boundary by applying -U<sub>B</sub> to the Teach-In input (yellow and green LEDs flash)
- 3. Disconnect the Teach-In input from -U<sub>B</sub> to save the window boundary
- 4. Place the target at the far end of the desired switch window
- 5. Program the window boundary by applying +U<sub>B</sub> to the Teach-In input (yellow and green LEDs flash)
- 6. Disconnect the Teach-In input from +U<sub>B</sub> to save the window boundary

#### Normally closed (NC) output

- 1. Place the target at the near end of the desired switch window
- 2. Program the window boundary by applying +U<sub>B</sub> to the Teach-In input (yellow and green LEDs flash)
- 3. Disconnect the Teach-In input from  $+U_B$  to save the window boundary
- 4. Place the target at the far end of the desired switch window
- 5. Program the window boundary by applying -U<sub>B</sub> to the Teach-In input (yellow and green LEDs flash)
- 6. Disconnect the Teach-In input from  $\mbox{-}U_B$  to save the window boundary

#### Switch Point Modes

# Normally open (NO) output

- 1. Place the target at the desired switch point position
- 2. Program the switch point by applying +U<sub>B</sub> to the Teach-In input (yellow and green LEDs flash)
- 3. Disconnect the Teach-In input from +UB to save the switch point
- 4. Cover the sensor face with hand or remove all objects from sensing range
- 5. Program the switch point by applying -U<sub>B</sub> to the Teach-In input (red and yellow LEDs flash)
- 6. Disconnect the Teach-In input from  $\mbox{-}U_B$  to save the switch point

## Normally closed (NC) output

- 1. Place the target at the desired switch point position
- 2. Program the switch point by applying  $-U_B$  to the Teach-In input (yellow and green LEDs flash)
- 3. Disconnect the Teach-In input from -U\_B to save the switch point
- 4. Cover the sensor face with hand or remove all objects from sensing range
- 5. Program the switch point by applying  $+U_B$  to the Teach-In input (red and yellow LEDs flash)
- 6. Disconnect the Teach-In input from  $+U_B$  to save the switch point

#### **Object Detection Mode**

- 1. Cover the sensor face with hand or remove all objects from sensing range
- 2. Apply -U<sub>B</sub> to the Teach-In input (red and yellow LEDs flash)
- 3. Disconnect the Teach-In input from +U<sub>B</sub> to save the setting
- 4. Apply +U<sub>B</sub> to the Teach-In input (red and yellow LEDs flash)
- 5. Disconnect the Teach-In input from  $+U_B$  to save the setting

#### **Factory settings**

See technical data.

## Display

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The sensor provides LEDs to indicate various conditions.

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	Green LED	Red LED	Yellow LED
During Normal operation			
Proper operation	On	Off	Switching state
Interference (e.g. compressed air)	Off	Flashing	Previous state
During sensor programming			
Object detected	Flashing	Off	Flashing
No object detected	Off	Flashing	Flashing
Object uncertain (programming invalid)	Off	Flashing	Flashing

#### Synchronization

This sensor features a synchronization input for suppressing ultrasonic mutual interference ("cross talk"). If this input is not connected, the sensor will operate using internally generated clock pulses. It can be synchronized by applying an external square wave. The pulse duration must be  $\geq$  100 µs. Each falling edge of the synchronization pulse triggers transmission of a single ultrasonic pulse. If the synchronization signal remains low for  $\geq$  1 second, the sensor will revert to normal operating mode. Normal operating mode can also be activated by opening the signal connection to the synchronization input (see note below).

If the synchronization input goes to a high level for > 1 second, the sensor will switch to standby mode, indicated by the green LED. In this mode, the outputs will remain in the last valid output state.

#### Note:

If the option for synchronization is not used, the synchronization input has to be connected to ground (0 V) or the sensor must be operated via a V1 cordset (4-pin).

The synchronization function cannot be activated during programming mode and vice versa.

#### The following synchronization modes are possible:

- 1. Several sensors (max. number see technical data) can be synchronized together by interconnecting their respective synchronization inputs. In this case, each sensor alternately transmits ultrasonic pulses in a self multiplexing mode. No two sensors will transmit pulses at the same time (see note below).
- 2. Multiple sensors can be controlled by the same external synchronization signal. In this mode the sensors are triggered in parallel and are synchronized by a common external synchronization pulse.
- 3. A separate synchronization pulse can be sent to each individual sensor. In this mode the sensors operate in external multiplex mode (see note below).
- 4. A high level (+U<sub>B</sub>) on the synchronization input switches the sensor to standby mode.

#### Note:

Sensor response times will increase proportionally to the number of sensors that are in the synchronization string. This is a result of the multiplexing of the ultrasonic transmit and receive signal and the resulting increase in the measurement cycle time.

#### Installation conditions

If the sensor is installed in an environment where the temperature can fall below 0 °C, one of these mounting flanges must be used for mounting: BF30, BF30-F, or BF 5-30.

If it is intended to operate the sensor at - 25 °C, we recommend discussing the mounting situation with a Pepperl + Fuchs application specialist to ensure a trouble-free operation.

If the sensor is mounted in a through hole using the included steel nuts, it must be mounted at the middle of the threaded housing. If it must be mounted at the front end of the threaded housing, plastic nuts with centering ring (optional accessories) must be used.

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