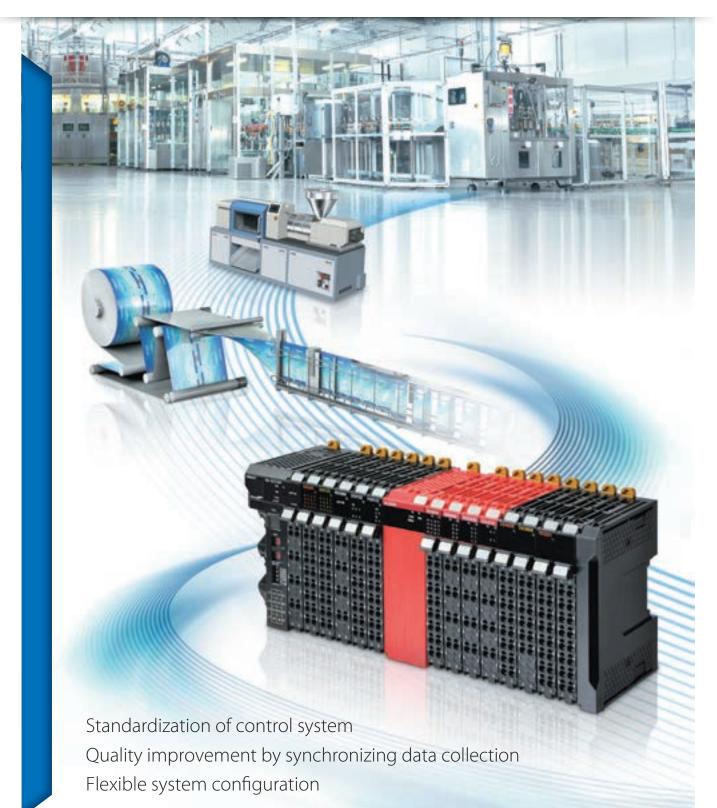
OMRON

NX-series I/O System

Unique I/O increases application quality and range



Unique I/O increases application quality and

The NX I/O connects sensors and actuators on production lines to optimize applications

Application example	IoT	Traceability	Measuring	Weighing
Value Design for Panel	IO-Link makes communication down to the sensor level visible	Easy and quick set-up for traceability using RFID	PLC systems can measure analog signals at high speeds for inspections	High-accuracy weighing using load cells
Corresponding to our shared Value Design for Panel concept for the specifications of	Applicable units: NX-ECC203 NX-ILM400	Applicable units: NX-V680C1 NX-V680C2	Applicable units: NX-HAD401	Applicable units: NX-RS1201
products				
				03200 AD4203 DA2603 DA3605 0 A 0 A 0 0 A 0 A 0 0 A 0 A 0 0 A 0 A 0 0 A 0 A 0 0 A 0 A 0 0 A 0 A 0 0 A 0 A 0 0 A 0 A 0 0 A 0 A 0 0 A 0 A 0 0 0 0 0 0 0 0 0 0 0 0 0 0 1 0 0 0 0 0 0 0 2 2 2 2 2 2 0 0 3 0 0 0 0 0 0 0 3 0 0

Communications coupler

• EtherCAT[®] • EtherNet/IP™

IO-Link master • Up to 4 IO-Link devices

with one master

Serial communications

· RS-232C or RS-422A/485 interface

New RFID

 Direct connection to V680 amplifiers and antennas

• 1 or 2 channels

Digital I/O

• 4, 8, 16, or 32 channels per input unit

• 2, 4, 8, 16, or 32 channels per output unit (8 channels per relay output unit)

16 channels per mixed
 I/O unit

 Standard, high-speed, and time-stamp models
 Units with Push-In

Plus/MIL/Fujitsu/M3 Screw connector

Analog I/O

- +/-10V voltage and 4-20 mA current signals
- 2, 4 or 8 channels per input unit

• 2 or 4 channels per output unit

Standard and

high-performance models

• Single-ended input and differential input models

New

High-speed analog inputs

4 channels per input unit
 Differential input

Sampling as fast as every 5 μs

Load cell inputs · One load cell with

one unit

Fastest conversion
 cycle of 125 μs

range

Temperature Servo press Safety control Motion control Simplify temperature control Simplify position control systems High-speed, Simplify safety control systems using temperature using pulse-train input type high-precision press systems sensors motors fit using load cells Applicable units: Applicable units: Applicable units: Applicable units: NX-RS1201 NX-SL3300 NX-TS3101 NX-ECS212 NX-SIH200 NX-SIH400 NX-HB3101 NX-PG0342-5 NX-SOD400 NX-SOH200 NX-TC3405 HB3101 New **End cover** Safety I/O **Temperature inputs Temperature control Position interface** • 4 or 8 safety input points per unit • Thermocouple or RTD inputs, • 2 or 4 multi-input Incremental and absolute 2 or 4 per unit (thermocouple and resistance encoder support • 2 or 4 safety output points per thermometer) channels per unit unit • Pulse output unit Conversion time of 10 ms, 60 ms or 250 ms (line driver output model) Conversion time of 50 ms Free allocation of the safety I/O units on the internal high speed \cdot Voltage output (for driving SSR) bus or linear current output Heater burnout • 1 CT input per channel Safety CPU detection • EN ISO13849-1 (PLe/Safety • 4 CT sensor inputs and 4 trigger Category 4), IEC 61508 (SIL3) outputs to drive SSRs certified Controls up to 128 safety I/O units

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Simplicity for advanced control

A fully integrated platform

The NX I/O is used to integrate sequence, motion, analog, vision, and safety control, previously done by PLC and dedicated controllers, and visualization of previously invisible sensor data within the Sysmac automation platform.

Sequence control

Multi-tasking and fully compliant with IEC 61131-3 standard programming and PLCopen[®] Function Blocks.







Motion control

PLCopen® Function Blocks for the motion control library are available to implement advanced motion control





PLCopent motion control

Analog control

The Sysmac Library* and instructions make temperature, weighing, and load control easier.



Weighing Control Library Servo Press Library



* The Sysmac Library is a collection of software functional components that can be used in programs for the NJ/NX/NY Controllers. Sample programs and HMI templates are also available. Download from Omron website and install to use in the Automation Software Sysmac Studio. http://www.ia.omron.com/sysmac_library/

	ming						HQQ	Contras
Program	m0 ×							Bendess Operation
	Name ResetW/10 SLC Activate EMO Active	Code Sype SAFEROOL SF_ESPE BOOL SF_EmergencyStep BOOL	Initial Value H4458 H4458 19448		Comment I			General Math Operators Other Operators Other Operators Safety Function blocks SP_Astenders Si 10M
	-d_Litopin d -d_litertAsset -S. Javolevet	zBing Bendy - Elitopous Erros - Diseponde -		AND	ECOL Serve ECOL Serve connecced	EDBO Sr_DS S_CONCONCOSE S_EDBL S_EDBL S_CONCONCOSE S_EDBL S_CONCONCOSE S_CONCOSE S_CONC		SF_ESR SF_CountLocking SF_CountMonitoring

Safety control

Conforms with PLCopen[®] Function Blocks for Safety.



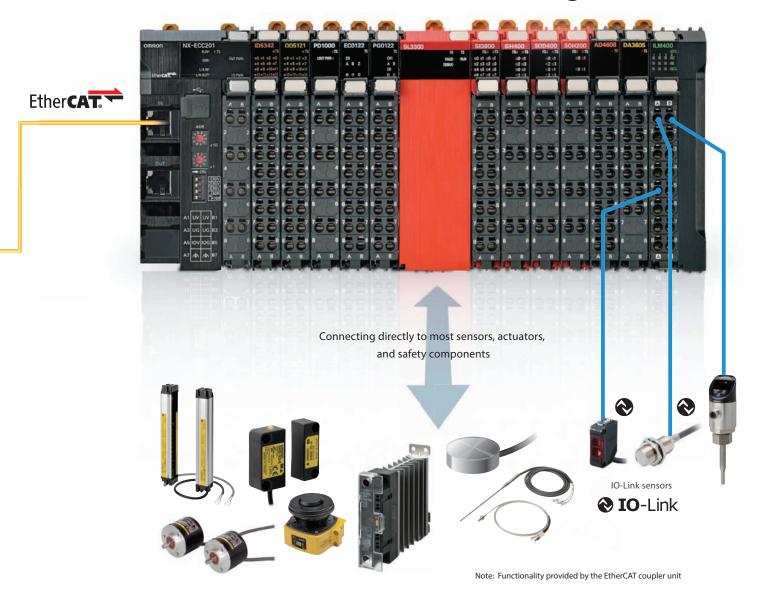
Feature of Sysma	IC
One Control through	
One Software and	
One Network	

Interfaces for sequence, motion, safety, and analog control and communications required for machines

Visualized sensor data

IO-Link makes communication down to the sensor level visible





Ether CAT.

Synchronized control for high-speed performance

Production data collection synchronized at high speed

Based on an internal high-speed bus running in synchronization with the EtherCAT network and CPU cycle, the NX I/O can be controlled and used for position, analog, and digital data collection with microsecond accuracy and with nanosecond resolution.

Feature High-speed I/O units accurately synchronized with the CPU cycle*1 · Digital I/O: High-speed and time-stamp models (NsynX) • Analog I/O: 10 µs conversion time per channel and 1:30000 resolution · Load cell inputs: 125 μs conversion time per channel and 24-bit resolution *1.Fastest cycle time: NX7=125 µs, NJ5=500 µs



Distributed clock

The EtherCAT node slave measures the time difference between incoming and returning frame - Time-Stamp function. With this Time-Stamp function the master can determine the propagation delay offset to the individual slave accurately. This mechanism ensures accurate synchronization between devices with less than 1 μ s jitter.

THERTYPE HEADER DATAGRA

DATAORAM 2

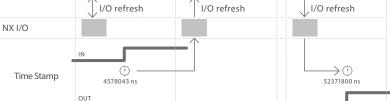
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500 μs

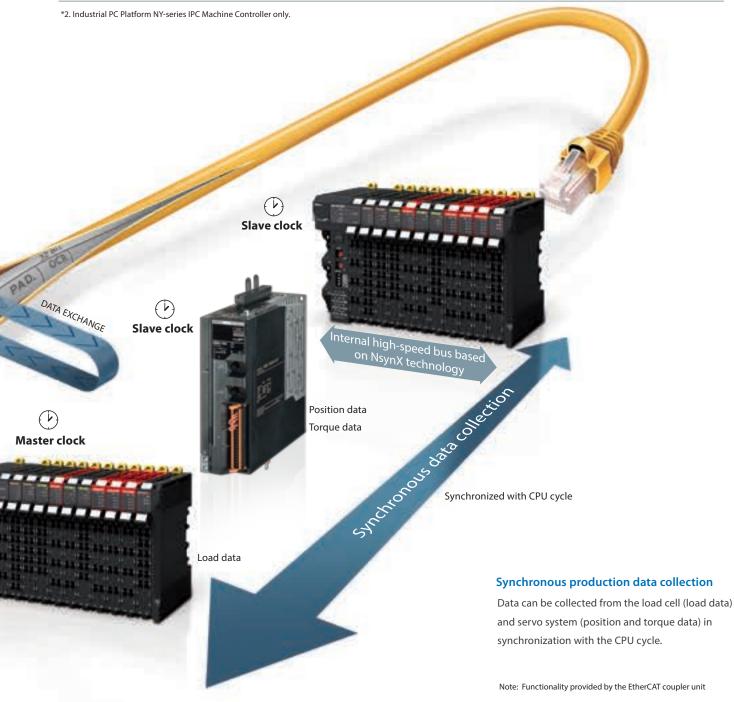
NsynX technology

- The NsynX technology is provided by the internal high-speed bus synchronized with the EtherCAT network. This technology is designed for machine control and includes:
- I/O units with distributed clock
- High-speed I/O units synchronized with the EtherCAT cycle
- I/O units with Time-Stamp function

Time Stamp sequence example EtherCAT cycle < 500 µs</td> >< 500 µs</td> NJ/NX/NY*2 Controller ↓ I/O refresh



Accurate control of input events and perfect control of output with nanosecond resolution



Simplify system configurations

The choice is yours

The modern control system demands increasing levels of flexibility.

The NX I/O enables connection with various controllers through the global standard network, which expands system configuration possibilities.

Modular remote I/O systems offer flexibility in I/O configuration and a wide choice of signal types and performance levels so that every I/O station can be assembled with just the right combination without changing the control architecture.



EtherCAT specification is governed by the EtherCAT Technology Group (ETG). EtherCAT is suitable for motion control and other applications that require high speed and high precision because of no need of handshaking and high bandwidth utilization.



NJ/NX/NY Series or EtherCAT master from other vendors

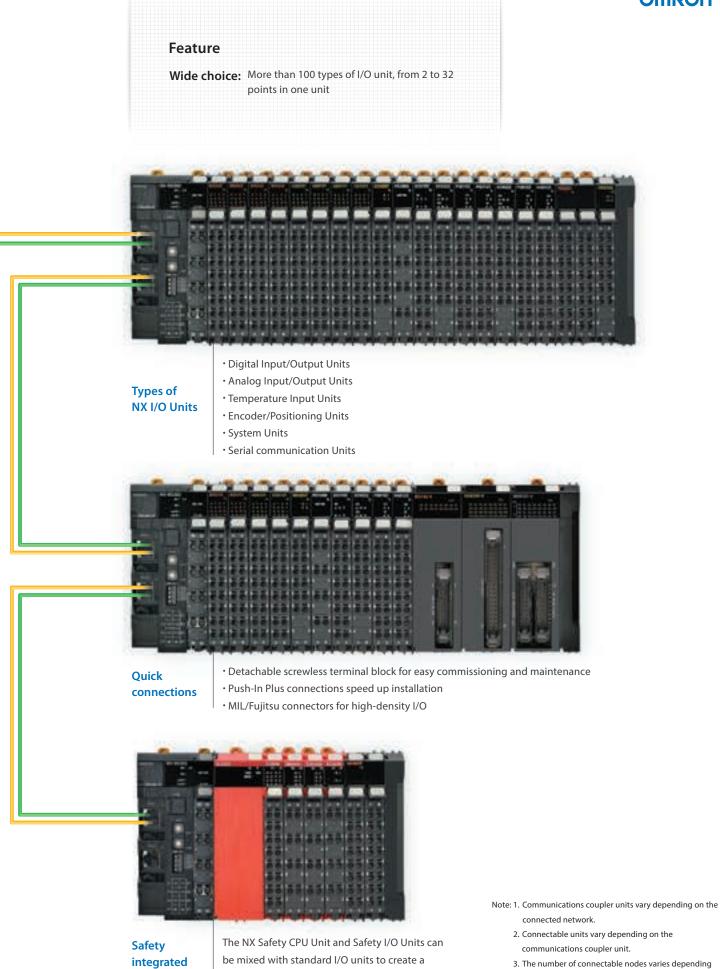
EtherNet/IP[®]

EtherNet/IP specification is governed by the Open DeviceNet Vendors Association (ODVA). Based on standardized Ethernet protocols (TCP/IP, UDP/IP), EtherNet/IP devices can be mixed with standard Ethernet devices.



CJ Series or PLC from other vendors

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complete modular safety control system

3. The number of connectable nodes varies depending on the master.

Downsize machines and control panels

Reduce wiring time and save space

Push-In Plus connections reduce the work and time required for wiring. Modular design saves space. Also designed for installation in any orientation, the NX I/O can be freely allocated in machines.



Up to 63 units per communication coupler

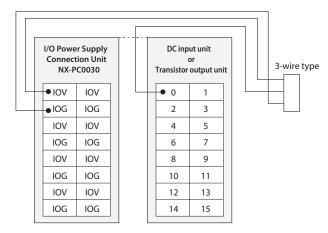


Corresponding to our shared Value Design for Panel concept for the specifications of products



Save space in control panels

V and G terminals are provided for each input signal (NX-PC0030). No relay terminal block is required, which saves space in control panels.



Greatly reduce wiring work with Push-In Plus terminal blocks

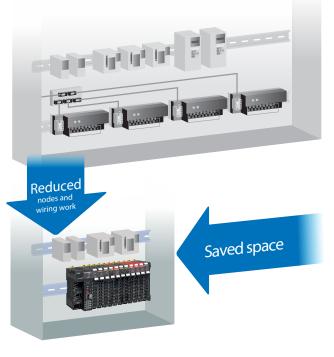
Push-In Plus terminal blocks make wiring work easy - just insert wires.



Conventional screw terminal block

Push-In Plus terminal block

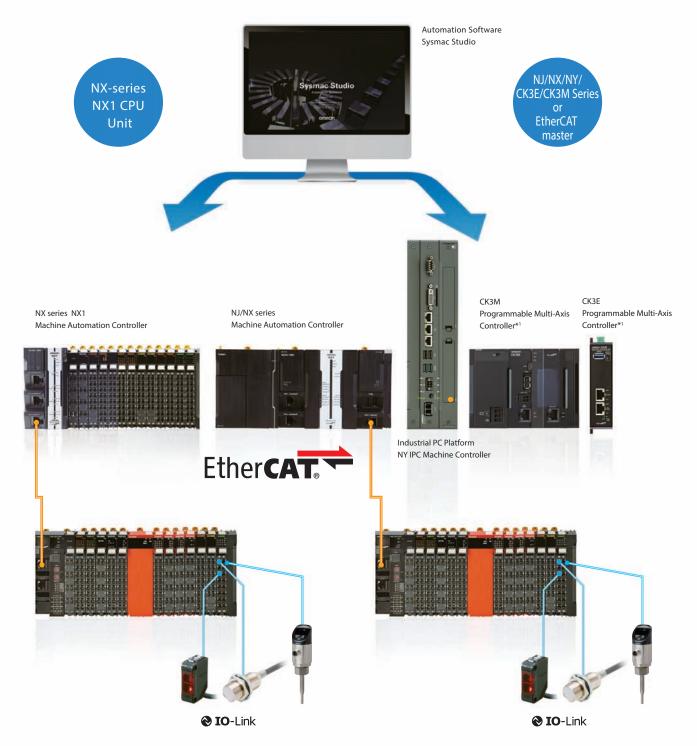
*1. Information for Push-In Plus and screw terminal blocks is based on Omron's actual measurement data.



Flexible connectivity expands system configuration possibilities

One I/O system for various controllers

While different machines may require different levels of controller performance, the NX I/O is the only remote I/O system you will need. This will unify wiring and installation techniques, and simplify spare parts stock.



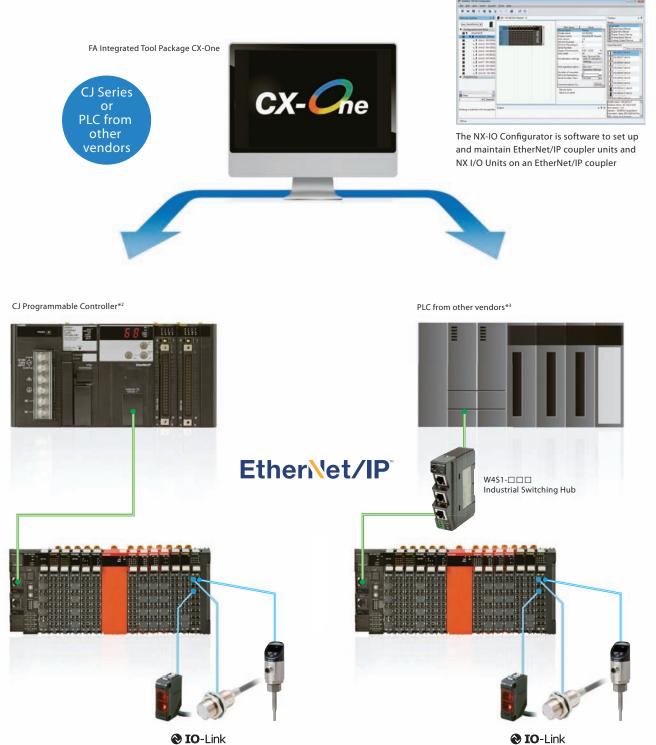
*1. Dedicated software is required to use the CK3M and CK3E Series.

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Features
Multivendor compatibility
The NX I/O can be connected with PLC from other vendors
as well as Omron PLC
• Start a small-scale IO-Link

IO-Link and other unique I/O systems can be easily integrated into

existing machine configurations



Easy configuration with NX-IO Configurator

*2. Dedicated software is required to use the CJ PLC or other vendor's PLC with the NX Safety Units. *3. Connect the NX I/O system to a PLC from another vendor via a switching hub and set up with the CX-One.

Various software components help reduce programming time

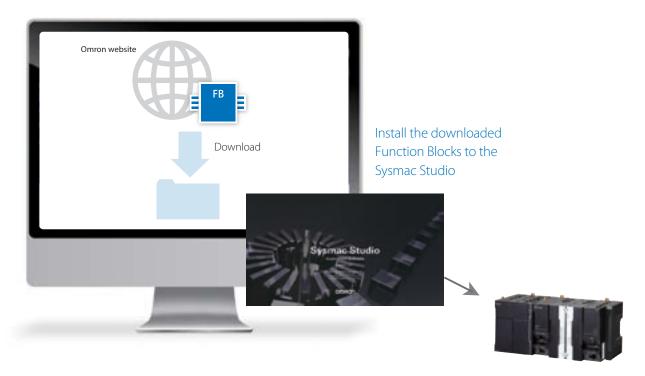
The Sysmac Library is a collection of software functional components that can be used in programs for the NJ/NX Machine Automation Controllers or Industrial PC Platform NY IPC Machine Controllers.

Packed with Omron's rich technical know-how on control programs, the Sysmac Library makes advanced control easy.



Easy-to-obtain Library

The Sysmac Library is freely available to download from Omron website. These software components specially designed for the NJ/NX/NY Controller can be used in your programs without the need for additional work.



Download from

http://www.ia.omron.com/sysmac_library/

Application example (1) Load cells

Press fit using servo press

Improve both speed and quality of the press-fit process

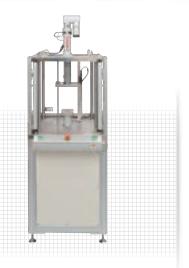
Load data is collected in synchronization with the CPU cycle for high-speed measurement, high-speed servo press control, and precision improvement.

Previous issues

· Wait time must be considered to operate the dedicated press controller together with the main PLC.

· Load, position, and torque data collected at the same time cannot

be checked from the host device.



NA HMI

1S AC

Servo

System

Servo press

. cylinder

Load cell

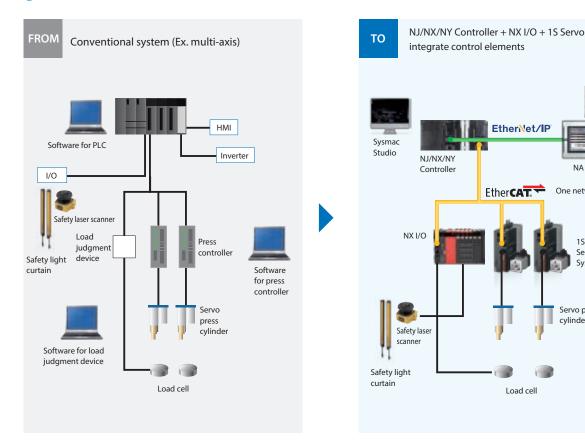
One network

Solution using Sysmac

One CPU system capable of switching between position, velocity, and torque control without stopping

• Fastest control cycle of 125 µs and servo press function using software for required control

· High-speed measurement and control by collecting load data synchronized with servo data (position and torque data).



Application example (2) Temperature control Packaging machines and molding machines (Temperature/motion/weighing)

Reduce material and design costs to implement temperature control

TCO can be reduced by eliminating the need for the dedicated temperature controller and reducing inventory control work and communications programming work.



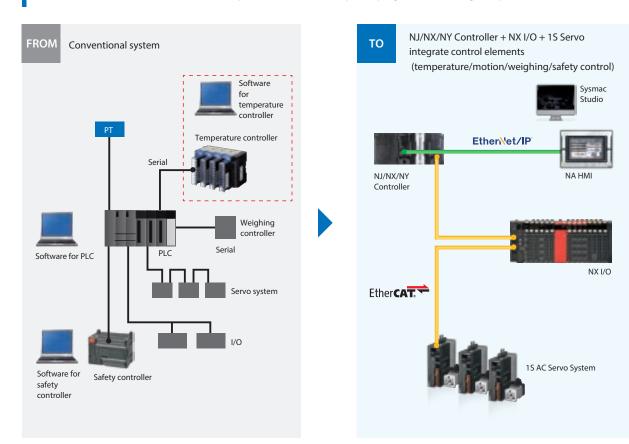
• Communications networks are selected for each device, and dedicated software for each component is used.

 Ladder program and memory configuration for communications are required.



Solution using Sysmac

Dedicated controllers, dedicated software, separate networks, and separate programs are no longer required



Application example (3) Photoelectric sensors and proximity sensors Improving system commissioning and changeover efficiency

Reduce work by individual identification

IO-Link sensors allow you to check individual sensor identifications in batches without going to the site, which results in a significant reduction of commissioning time.



Application example (4) Traceability using RFID Improving system commissioning efficiency

Reduce time required for system design and wiring

Distributed installation of RFID units simplifies system design and wiring, even for high-mix production.

Previous issues

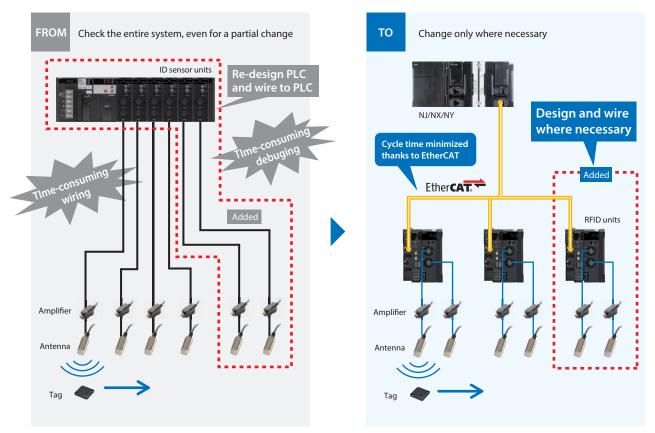
 When the system configuration is changed, it requires considerable time and effort to re-design and debug the entire program because ID sensor units cannot be distributed.

 \cdot It is difficult and time-consuming to wire an additional antenna to the ID

sensor unit that is located away from it.

Solution using Sysmac

• The RFID units can be installed near each antenna, allowing addition or change of programs only where necessary and reducing wiring time



EtherNet/IP connection is also available.

Slave Terminals NX Series

Ordering Information

Applicable standards

Refer to the OMRON website (www.ia.omron.com) or ask your OMRON representative for the most recent applicable standards for each model.

Communications Coupler Units • EtherCAT Coupler Units

Product name	Communications cycle in DC Mode	Current consumption	Maximum I/O power sup- ply current	Model
EtherCAT Coupler Unit *1	250 to 4000 μs * 2	1.45 W or lower	4 A	NX-ECC201
	250 to 4000 μs * 2	1.45 W of lower		NX-ECC202
	125 to 10000 μs * 2	1.25 W or lower	10 A	NX-ECC203

***1.** One End Cover NX-END01 is provided with the EtherCAT Coupler Unit.

*2. This depends on the specifications of the EtherCAT master. For example, the values are as follows when the EtherCAT Coupler Unit is connected to the built-in EtherCAT port on an NJ5-series CPU Unit: 500 μs, 1,000 μs, 2,000 μs, and 4,000 μs. For the specifications of the built-in EtherCAT port, refer to the user's manual for the built-in EtherCAT port on the connected CPU Unit or the Industrial PC. This depends on the Unit configuration.

• EtherNet/IP Coupler Unit

Product name	Current consumption	Maximum I/O power supply current	Model
EtherNet/IP Coupler Unit *			
	1.60 W or lower	10 A	NX-EIC202

*One End Cover NX-END01 is provided with the EtherCAT Coupler Unit.

Digital Input Units

	Specifications					
Product Name	Number of points	Internal I/O common	Rated input voltage	I/O refreshing method	ON/OFF response time	Model
			12 to 24 VDC	Switching Synchronous I/O	20 μs max./400 μs max.	NX-ID3317
		NPN		refreshing and Free-Run refreshing		NX-ID3343
DC Input Unit	4 points		24 VDC	Input refreshing with input changed time only *	100 ns max./100 ns max.	NX-ID3344
	4 points		12 to 24 VDC	Switching Synchronous I/O	20 μs max./400 μs max.	NX-ID3417
		PNP		refreshing and Free-Run refreshing	- 100 ns max./100 ns max.	NX-ID3443
(Screwless				Input refreshing with input changed time only *		NX-ID3444
Clamping Terminal	8 points	NPN	24 VDC	Switching Synchronous I/O refreshing and Free-Run refreshing	20 μs max./400 μs max.	NX-ID4342
Block, 12 mm Width)	o points	PNP				NX-ID4442
	16 points	NPN				NX-ID5342
	10 points	PNP				NX-ID5442
DC Input Unit	16 points	For both NPN/PNP	24 VDC	Switching Synchronous I/O refreshing and Free-Run refreshing	20 μs max./400 μs max.	NX-ID5142-1

	Specifications					
Product Name	Number of points	Internal I/O common	Rated input voltage	I/O refreshing method	ON/OFF response time	Model
DC Input Unit	16 points	For both		Switching Synchronous I/O		NX-ID5142-5
(MIL Connector, 30 mm Width)		NPN/PNP	24 VDC	refreshing and Free-Run refreshing	20 μs max./400 μs max.	NX-ID6142-5
DC Input Unit	32 points	For both NPN/PNP	24 VDC	Switching Synchronous I/O refreshing and Free-Run refreshing	20 μs max./400 μs max.	NX-ID6142-6
AC Input Unit (Screwless Clamping Terminal Block, 12 mm Width)	4 points		VAC, 50/60 Hz VAC, ±3 Hz)	Free-Run refreshing	10 ms max./40 ms max.	NX-IA3117

* To use input refreshing with input changed time, the EtherCAT Coupler Unit with unit version 1.1 or later and the Sysmac Studio version 1.07 or higher are required.

Digital Output Units

	Specifications							
Product Name	Number of points	Internal I/O common	Maximum value of load current	Rated voltage	I/O refreshing method	ON/OFF response time	Model	
	2	NPN	0.5 A/point, 1 A/	24 VDC	Output refreshing with	300 ns max./	NX-OD2154	
	<u> </u>	PNP	Unit	24 000	specified time stamp only *	300 ns max.	NX-OD2258	
		NPN		12 to 24 VDC		0.1 ms max./ 0.8 ms max.	NX-OD3121	
Transistor Output		INFIN	0.5 A/point, 2 A/			300 ns max./ 300 ns max.	NX-OD3153	
Unit	4		Unit	24 VDC		0.5 ms max./ 1.0 ms max.	NX-OD3256	
		PNP		24 VDC		300 ns max./ 300 ns max.	NX-OD3257	
			2 A/point, 8 A/ Unit		Switching Synchronous I/O refreshing and Free- Run refreshing	0.5 ms max./ 1.0 ms max.	NX-OD3268	
(Screwless Clamping Terminal		NPN		12 to 24 VDC		0.1 ms max./ 0.8 ms max.	NX-OD4121	
Block, 12 mm Width)	8	PNP	0.5 A/point, 4 A/	24 VDC		0.5 ms max./ 1.0 ms max.	NX-OD4256	
	10	NPN	Unit	12 to 24 VDC		0.1 ms max./ 0.8 ms max.	NX-OD5121	
	10	16 PNP		24 VDC		0.5 ms max./ 1.0 ms max.	NX-OD5256	
Transistor Output Unit		NPN		12 to 24 VDC	Switching Synchronous I/O	0.1 ms max./ 0.8 ms max.	NX-OD5121-1	
(M3 Screw Terminal Block, 30 mm Width)	16 PNP		- 0.5 A/point, 5 A/ Unit	24 VDC	refreshing and Free- Run refreshing	0.5 ms max./ 1.0 ms max.	NX-OD5256-1	

	Specifications						
Product Name	Number of points	Internal I/O common	Maximum value of load current	Rated voltage	I/O refreshing method	ON/OFF response time	Model
Transistor Output Unit	16	NPN	0.5 A/point, 2 A/	12 to 24 VDC		0.1 ms max./ 0.8 ms max.	NX-OD5121-5
	10	PNP	Unit	24 VDC	Switching Synchronous I/O	0.5 ms max./ 1.0 ms max.	NX-OD5256-5
1	32	NPN	0.5 A/point, 2 A/	12 to 24 VDC	refreshing and Free- Run refreshing	0.1 ms max./ 0.8 ms max.	NX-OD6121-5
(MIL Connector, 30 mm Width)	32	PNP	common, 4 A/ Unit	24 VDC		0.5 ms max./ 1.0 ms max.	NX-OD6256-5
Transistor Output Unit (Fujitsu Connector, 30 mm Width)	32	NPN	0.5 A/point, 2 A/ common, 4 A/ Unit	12 to 24 VDC	Switching Synchronous I/O refreshing and Free- Run refreshing	0.1 ms max./ 0.8 ms max.	NX-OD6121-6
Relay Output Unit	0	Relay type: N.O.	250 VAC/2 A (cos VAC/	φ=1), 250		15 ms max./ 15 ms max.	NX-OC2633
	2	Relay type: N.O.+N.C.	2 A (cosǫ=0.4), 24 A/Unit	4 VDC/2 A, 4	Free-Run refreshing		NX-OC2733
(Screwless Clamping Terminal Block, 12 mm Width/ 24 mm Width)	8	Relay type: N.O.	250 VAC/2 A (cos VAC/ 2 A (cosφ=0.4), 24 A/Unit	4 VDC/2 A, 8	Free-Run refreshing	15 ms max./ 15 ms max.	NX-OC4633

* To use output refreshing with specified time stamp, the EtherCAT Coupler Unit with unit version 1.1 or later and the Sysmac Studio version 1.07 or higher are required.

Digital Mixed I/O Units

	Specifications							
Product Name	Number of points	Internal I/O common	Maximum value of load current	I/O refreshing method	ON/OFF response time	Model		
DC Input/Transistor Output Unit	Outputs: 16 points	Outputs: NPN Inputs: For both NPN/ PNP	Outputs: 12 to 24 VDC Inputs: 24 VDC	Switching Synchronous I/O	Outputs: 0.1 ms max./ 0.8 ms max. Inputs: 20 µs max./ 400 µs max.	NX-MD6121-5		
(MIL Connector, 30 mm Width)	İnputs: 16 points	refr	refreshing and Free- Run refreshing	Outputs: 0.5 ms max./ 1.0 ms max. Inputs: 20 µs max./ 400 µs max.	NX-MD6256-5			
DC Input/Transistor Output Unit (Fujitsu Connector, 30 mm Width)	Outputs: 16 points Inputs: 16 points	Outputs: NPN Inputs: For both NPN/ PNP	Outputs: 12 to 24 VDC Inputs: 24 VDC	Switching Synchronous I/O refreshing and Free- Run refreshing	Outputs: 0.1 ms max./ 0.8 ms max. Inputs: 20 μs max./ 400 μs max.	NX-MD6121-6		

Pattern	Configuration	Number of connectors	Branching
A	Connecting Cable Connector-Terminal Block Conversion Unit 20 or 40 terminals		None
В	Connecting Cable with two branches Connector-Terminal Block Conversion Unit 20 terminals 20 terminals		2 branches
С	Connecting Cable Connector-Terminal Block Conversion Unit 20 terminals 20 terminals	2	None

Connection Patterns for Connector-Terminal Block Conversion Units

Connections to Connector-Terminal Block Conversion Units

Unit	I/O capacity	Number of connectors	Polarity	Connection pattern	Connecting Cable *1	Connector-Terminal Block Conversion Unit	Wiring method	Common terminal
NX-ID5142-5	16 inputs	1 MIL connector	NPN/ PNP	A	XW2Z-□□□X	XW2R-□20GD-T	Depends on model *3	None
		connector	PNP		XW2Z-□□□X	XW2D-20G6	Phillips screw	None
				A	XW2Z-DDDPM	XW2R-□34GD-C2	Depends on model *3	None
				Α	XW2Z-DDK	XW2D-40G6	Phillips screw	None
				в	XW2Z-DDN	XW2R-□20GD-T (2 Units)	Depends on model *3	None
NX-ID6142-5	32 inputs	1 MIL connector	NPN/ PNP	В	XW2Z-DDN	XW2C-20G5-IN16 (2 Units) *2	Phillips screw	Yes
				В	XW2Z-	XW2C-20G6-IO16 (2 Units)	Phillips screw	Yes
				В	XW2Z-	XW2D-20G6 (2 Units)	Phillips screw	None
				в	XW2Z-DDN	XW2E-20G5-IN16 (2 Units) *2	Phillips screw	Yes
				A	XW2Z-DDPF	XW2R-□34GD-C1	Depends on model *3	None
				А	XW2Z-DDB	XW2D-40G6	Phillips screw	None
				в	XW2Z-DDD	XW2R-□20GD-T (2 Units)	Depends on model *3	None
NX-ID6142-6	32 inputs	1 Fujitsu connector	NPN/ PNP	в	XW2Z-DDD	XW2C-20G5-IN16 (2 Units) *2	Phillips screw	Yes
				В	XW2Z-□□□D	XW2C-20G6-IO16 (2 Units)	Phillips screw	Yes
				В	XW2Z-□□□D	XW2D-20G6 (2 Units)	Phillips screw	None
				В	XW2Z-DDD	XW2E-20G5-IN16 (2 Units) *2	Phillips screw	Yes
NX-OD5121-5	16 outputs	1 MIL	NPN	A	XW2Z-□□X	XW2R-□20GD-T	Depends on model *3	None
		connector		A	XW2Z-□□□X	XW2D-20G6	Phillips screw	None
NX-OD5256-5	16 outputs	1 MIL connector	PNP	A	XW2Z-DDX	XW2R-□20GD-T	Depends on model *3	None
	-	CONTRECTOR		Α	XW2Z-□□□X	XW2D-20G6	Phillips screw	None

Unit	I/O capacity	Number of connectors	Polarity	Connection pattern	Connecting Cable * 1	Connector-Terminal Block Conversion Unit	Wiring method	Common terminal
				А	XW2Z-DDDPM	XW2R-□34GD-C4	Depends on model *3	None
				A	XW2Z-□□□K	XW2D-40G6	Phillips screw	None
NX-OD6121-5	32 inputs	1 MIL connector	NPN	В	XW2Z-DDN	XW2R-□20GD-T (2 Units)	Depends on model * 3	None
				В	XW2Z-	XW2C-20G6-IO16 (2 Units)	Phillips screw	Yes
				В	XW2Z-	XW2D-20G6 (2 Units)	Phillips screw	None
				А	XW2Z-DDPF	XW2R-□34GD-C3	Depends on model * 3	None
				A	XW2Z-	XW2D-40G6	Phillips screw	None
NX-OD6121-6	32 inputs	1 Fujitsu connector	NPN	В	XW2Z-DDL	XW2R-□20GD-T (2 Units)	Depends on model * 3	None
				В	XW2Z-DDDL	XW2C-20G6-IO16 (2 Units)	Phillips screw	Yes
				В	XW2Z-DDDL	XW2D-20G6 (2 Units)	Phillips screw	None
				A	XW2Z-DDDPM	XW2R-□34GD-C4	Depends on model *3	None
				A	XW2Z-□□□K	XW2D-40G6	Phillips screw	None
NX-OD6256-5	32 inputs	1 MIL connector	PNP	В	XW2Z-DDN	XW2R-□20GD-T (2 Units)	Depends on model *3	None
				В	XW2Z-DDN	XW2C-20G6-IO16 (2 Units)	Phillips screw	Yes
				В	XW2Z-DDN	XW2D-20G6 (2 Units)	Phillips screw	None
	16 outputs	1 MIL	NPN/ PNP	С	XW2Z-□□□X	XW2R-🗆20GD-T	Depends on model *3	None
NX-MD6121-5		connector	FINE	С	XW2Z-□□□X	XW2D-20G6	Phillips screw	None
NA-WD0121-5	16 outputs	1 MIL	NPN	С	XW2Z-□□□X	XW2R-🗆20GD-T	Depends on model *3	None
		connector		С	XW2Z-□□□X	XW2D-20G6	Phillips screw	None
				С	XW2Z-□□□A	XW2R-D20GD-T	Depends on model *3	None
		1 Fuiitsu	NPN/	С	XW2Z-🗆 🗆 A	XW2C-20G5-IN16 *2	Phillips screw	Yes
	16 outputs	connector	PNP	С	XW2Z-🗆 🗆 A	XW2C-20G6-IO16	Phillips screw	Yes
NX-MD6121-6				С	XW2Z-🗆 🗆 A	XW2D-20G6	Phillips screw	None
				С	XW2Z-🗆 🗆 A	XW2E-20G5-IN16 *2	Phillips screw	Yes
		1 Fujitsu		С	XW2Z-□□□A	XW2R-□20GD-T	Depends on model *3	None
	16 outputs	connector	NPN	С	XW2Z-🗆 🗆 A	XW2C-20G6-IO16	Phillips screw	Yes
				С	XW2Z-□□□A	XW2D-20G6	Phillips screw	None
	16 outputs	1 MIL connector	NPN/ PNP	С	XW2Z-□□□X	XW2R-□20GD-T	Depends on model *3	None
NX-MD6256-5		CONTECIOI	1-111	С	XW2Z-□□□X	XW2D-20G6	Phillips screw	None
	16 outputs	1 MIL	PNP	С	XW2Z-□□□X	XW2R-D20GD-T	Depends on model *3	None
		connector		С	XW2Z-DDDX	XW2D-20G6	Phillips screw	None

Note: For other models and specifications that are not listed above, refer to the XW2R Series Connector-Terminal Block Conversion Units Catalog (Cat. No. G077) and XW2R Datasheets.

*1. Din the model number indicates the cable length. Refer to the XW2Z Datasheet for details.

***2.** The inputs are NPN. For PNP inputs, reverse the polarity of the external power supply connections to the power supply terminals on the Connector-Terminal Block Conversion Unit.

***3.** The wiring methods vary depending on the Connector-Terminal Block Conversion Unit. □ in the model number indicates the wiring method. J = Phillips screw

E = Slotted screw (rise up)

P = Push-in spring

Pattern	Configuration	Number of connectors	Branching
A	Connecting Cable	1	2 branches
E	I/O Relay Terminal Connecting Cable	2	None
F	Connecting Cable	1	

Connection Patterns for I/O Relay Terminals

Connections to I/O Relay Terminals

Unit	I/O capacity	Number of connectors	Polarity	Connection pattern	Number of branches	Connecting Cable *1	I/O Relay Terminal	Wiring method
				F	None	XW2Z-RO□C	G7TC-ID16	Phillips screwPhillips screwPush-in springP-C16Push-in springP-C16Push-in springP-1Push-in springP-1Push-in springP-1-C16Push-in springP-1-C16Push-in springP-1Push-in springP-C16Push-in springP-C16Push-in springP-1-C16Push-in springP-1-C16Puillips screwP-1-C16Puillips screwP-1-C16Puillips screwP-1-D19Puillips screwP-1-D19Puillips screwP-1-D19Puillips screwP-1-D19Puillips screwP-1-D19Puillips screw
			NPN	F	None	XW2Z-RO□C	G7TC-IA16	
	10 :	1 MIL	INPIN	F	None	XW2Z-RO□C	G70V-SID16P	
NX-ID5142-5	16 inputs	connector		F	None	XW2Z-RO□C	G70V-SID16P-C16	
			PNP	F	None	XW2Z-RO□C	G70V-SID16P-1	
			FINE	F	None	XW2Z-RO□C	G70V-SID16P-1-C16	Push-in spring
				A	2	XW2Z-RO□-□-D1	G7TC-ID16	Phillips screw
			NPN	A	2	XW2Z-RO□-□-D1	G7TC-IA16	Phillips screw
NX-ID6142-5	20 inputo	1 MIL		A	2	XW2Z-RO□-□-D1	G70V-SID16P	Phillips screwPhillips screwPush-in springPush-in springPush-in springPush-in springPush-in springPhillips screwPhillips screwPush-in springPhillips screwPush-in springPush-in springPush-in springPush-in springPush-in springPush-in springPhillips screwPhillips screwPush-in springPush-in springPush-in springPush-in springPush-in springPush-in springPush-in springPush-in springPush-in springPhillips screwPhillips screw
NX-ID0142-5	32 inputs	connector		A	2	XW2Z-RO□-□-D1	G70V-SID16P-C16	Push-in spring
			PNP	A	2	XW2Z-RO -D1	G70V-SID16P-1	Push-in spring
			FINE	A	2	XW2Z-RO□-□-D1	G70V-SID16P-1-C16	Push-in spring
				A	2	XW2Z-RI□C-□	G7TC-ID16	Phillips screwPush-in springPush-in springPush-in springPush-in springPhillips screwPhillips screwPush-in springPush-in springPush-in springPush-in springPush-in springPhillips screwPush-in springPush-in springPhillips screwPhillips screwPush-in springPush-in springPush-in springPush-in springPush-in springPush-in springPhillips screwPhillips screw
			NPN	A	2	XW2Z-RI□C-□	G7TC-IA16	
NX-ID6142-6	00 innuto	1 Fujitsu	INFIN	A	2	XW2Z-RI□C-□	G70V-SID16P	
NX-ID0142-0	32 inputs	connector		A	2	XW2Z-RI□C-□	G70V-SID16P-C16	Push-in spring
			PNP	A	2	XW2Z-RI□C-□	G70V-SID16P-1	Push-in spring
			FINE	A	2	XW2Z-RI□C-□	G70V-SID16P-1-C16	Push-in spring
				F	None	XW2Z-RO□C	G7TC-OC08	Phillips screw
				F	None	XW2Z-RO□C	G70D-SOC08	Phillips screw
				F	None	XW2Z-RO□C	G70R-SOC08 *2	Phillips screw
				F	None	XW2Z-RO□C	G7TC-OC16	Phillips screw
				F	None	XW2Z-RO□C	G70D-SOC16	Phillips screw
NX-OD5121-5	16 outputs	1 MIL connector	NPN	F	None	XW2Z-RO□C	G70D-VSOC16	Phillips screw
	Calpulo			F	None	XW2Z-RO□C	G70D-FOM16	Phillips screw
				F	None	XW2Z-RO□C	G70D-VFOM16	Phillips screw
				F	None	XW2Z-RO□C	G70A-ZOC16-3	Phillips screw
				F	None	XW2Z-RO□C	G70V-SOC16P	Push-in spring
				F	None	XW2Z-RO□C	G70V-SOC16P-C4	Push-in spring

Unit	I/O capacity	Number of connectors	Polarity	Connection pattern	Number of branches	Connecting Cable *1	I/O Relay Terminal	Wiring method
				F	None	XW2Z-RI□C	G7TC-OC16-1	Phillips screw
				F	None	XW2Z-RO□C	G70D-SOC16-1	Phillips screw
NX-OD5256-5	16	1 MIL	PNP	F	None	XW2Z-RO□C	G70D-FOM16-1	Phillips screw
NA-OD5250-5	outputs	connector	FINE	F	None	XW2Z-RO□C	G70A-ZOC16-4	Phillips screw
				F	None	XW2Z-RO□C	G70V-SOC16P-1	Push-in spring
				F	None	XW2Z-RO□C	G70V-SOC16P-1-C4	Push-in spring
				A	2	XW2Z-RO□-□-D1	G7TC-OC16	Phillips screw
				A	2	XW2Z-RO□-□-D1	G7TC-OC08	Phillips screw
				А	2	XW2Z-RO□-□-D1	G70D-SOC16	Phillips screw
				A	2	XW2Z-RO□-□-D1	G70D-FOM16	Phillips screw
				A	2	XW2Z-RO□-□-D1	G70D-VSOC16	Phillips screw
NX-OD6121-5	32	1 MIL	NPN	А	2	XW2Z-RO□-□-D1	G70D-VFOM16	Phillips screw
	outputs	connector		А	2	XW2Z-RO□-□-D1	G70A-ZOC16-3 and Relay	Phillips screw
				А	2	XW2Z-RO□-□-D1	G70R-SOC08 *2	Phillips screw
				А	2	XW2Z-RO□-□-D1	G70D-SOC08	Phillips screw
				А	2	XW2Z-RO -D1	G70V-SOC16P	Push-in spring
				А	2	XW2Z-RO□-□-D1	G70V-SOC16P-C4	Push-in spring
				А	2	XW2Z-RO□C-□	G7TC-OC16	Phillips screw
				А	2	XW2Z-RO□C-□	G7TC-OC08	Phillips screw
				А	2	XW2Z-RO□C-□	G70D-SOC16	Phillips screw
				Α	2	XW2Z-RO□C-□	G70D-FOM16	Phillips screw Phillips screw Phillips screw Push-in spring Phillips screw Phillips screw
				А	2	XW2Z-RO□C-□	G70D-VSOC16	
NX-OD6121-6	32	1 Fujitsu	NPN	А	2	XW2Z-RO□C-□	G70D-VFOM16	
NX-OD0121-0	outputs	connector	INPIN	А	2	XW2Z-RO□C-□	G70A-ZOC16-3 and Relay	
				А	2	XW2Z-RO□C-□	G70R-SOC08 *2	Phillips screw
				Α	2	XW2Z-RO□C-□	G70D-SOC08	Phillips screw
				А	2	XW2Z-RO□C-□	G70V-SOC16P	
				А	2	XW2Z-RO□C-□	G70V-SOC16P-C4	
				А	2	XW2Z-RI□-□-D1	G7TC-OC16-1	
				А	2	XW2Z-RO -D1	G70D-SOC16-1	
				А	2	XW2Z-RO -D1	G70D-FOM16-1	
NX-OD6256-5	32 outputs	1 MIL connector	PNP	А	2	XW2Z-RO□-□-D1	G70A-ZOC16-4 and Relay	Phillips screw
				А	2	XW2Z-RO -D1	G70V-SOC16P-1	Push-in spring
				А	2	XW2Z-RO -D1	G70V-SOC16P-1-C4	1 0
				E	None	XW2Z-RO□C	G7TC-ID16	
		1 MIL		E	None	XW2Z-RO□C	G7TC-IA16	
	16 inputs	connector	NPN	E	None	XW2Z-RO□C	G70V-SID16P	
				E	None	XW2Z-RO□C	G70V-SID16P-C16	
				E	None	XW2Z-RO□C	G7TC-OC16	
				E	None	XW2Z-RO□C	G7TC-OC08	
				E	None	XW2Z-RO□C	G70D-SOC16	-
				E	None	XW2Z-RO□C	G70D-FOM16	
NX-MD6121-5				E	None	XW2Z-RO□C	G70D-VSOC16	
	16	1 MIL		E	None	XW2Z-RO□C	G70D-VFOM16	
	outputs	connector	NPN			XW2Z-RO□C	G70A-ZOC16-3 and Relay	
				E	None	XW2Z-RO□C	G70R-SOC08 *2	Phillips screw
				E	None	XW2Z-RO□C	G70D-SOC08	-
				E	None	XW2Z-RO□C	G70V-SOC16P	
			1	E	None	XW2Z-RO□C	G70V-SOC16P-C4	

Slave Terminals NX Series

Unit	I/O capacity	Number of connectors	Polarity	Connection pattern	Number of branches	Connecting Cable *1	I/O Relay Terminal	Wiring method	
				E	None	XW2Z-R□C	G7TC-ID16	Phillips screw	
	10 :	1 Fujitsu	NPN	E	None	XW2Z-R□C	G7TC-IA16	Phillips screw Phillips screw Push-in spring Push-in spring Phillips screw Push-in spring Push-in spring Push-in spring Phillips screw	
	16 inputs	connector	INPIN	E	None	XW2Z-R□C	G70V-SID16P		
				E	None	XW2Z-R□C	G70V-SID16P-C16	Push-in spring	
				E	None	XW2Z-R□C	G7TC-OC16	Phillips screw	
NX-MD6121-6				E	None	XW2Z-R□C	G7TC-OC08	Phillips screw	
				E	None	XW2Z-R□C	G70D-SOC16	Phillips screw	
				E	None	XW2Z-R□C	G70D-FOM16	Phillips screw	
				E	None	XW2Z-R□C	G70D-VSOC16	Phillips screw	
	16	1 Fujitsu	NPN	E	None	XW2Z-R□C	G70D-VFOM16	Phillips screw Phillips screw Push-in spring 16 Push-in spring Phillips screw Push-in spring Push-in spring Push-in spring Phillips screw Phillips screw Phillips screw Push-in spring C16 Push-in spring Phillips screw Phillips screw	
	outputs	connector		E	None	XW2Z-R□C	G70A-ZOC16-3 and Relay		
				E	None	XW2Z-R□C	G70R-SOC08 *2	Phillips screw	
				E	None	XW2Z-R□C	G70D-SOC08	Phillips screw	
				E	None	XW2Z-R□C	G70V-SOC16P	Phillips screw Phillips screw Push-in spring Push-in spring Phillips screw Push-in spring Push-in spring Push-in spring Phillips screw Phillips screw Push-in spring Push-in spring Phillips screw	
				E	None	XW2Z-R□C	G70V-SOC16P-C4	Push-in spring	
	16 inputs	1 MIL	PNP	E	None	XW2Z-RO□C	G70V-SID16P-1	Push-in spring	
	ro inputs	connector	FINE	E	None	XW2Z-RO□C	G70V-SID16P-1-C16	Push-in spring	
				E	None	XW2Z-RO□C	G7TC-OC16-1	Phillips screw	
				E	None	XW2Z-RI□C	G70D-SOC16-1	Phillips screw	
NX-MD6256-5	10	4 1 1		E	None	XW2Z-RI□C	G70D-FOM16-1	Phillips screw	
	16 outputs	1 MIL connector	PNP	E	None	XW2Z-RI□C	G70A-ZOC16-4 and Relay	Phillips screw	
				E	None	XW2Z-RI□C	G70V-SOC16P-1	Push-in spring	
				E	None	XW2Z-RI□C	G70V-SOC16P-1-C4	Push-in spring	

Note: 1. For other models and specifications that are not listed above, refer to the datasheets.
2. The G70V Series includes models that provide internal connections. Refer to the *G70V Datasheet* (Cat. No. J215) for details.

3. The G70A is a socket only. Mountable relays and timers are sold separately.
*1. in the model number indicates the cable length. Refer to the XW2Z-R Datasheet (Cat. No. G126) for details.

***2.** Product no longer available to order.

High-speed Analog Input Units

				Sp	ecification				
Product	Number	Innut		Innut	Conversion	Trigger in	put section	I/O	Model
name	of points	Input range	Resolution	Input method	time	Number of points	Internal I/O common	refreshing method	
High-speed Analog Input Units	4 nointe	-10 to +10V -5 to +5V 0 to 10V	 Input range of -10 to 10 V or -5 to 5 V: 1/64,000 	Differential	E us an shared		NPN	Synchronou	NX-HAD401
	4 points	0 to 5V 1 to 5V 0 to 20mA 4 to 20mA	(full scale) • Other input range: 1/32,000 (full scale)	Differential input	5 μs per channel	4	PNP	- s I/O refreshing	NX-HAD402

Analog Input Units

	Specification													
Product name	Number of points	Input range	Resolution	Conversion value, decimal number (0 to 100%)	Over all accuracy (25°C)	Input method	Conversion time	Input imped ance	I/O refreshing method	Model				
					.0.00/	Single-ended input			Free Dure	NX-AD2603 NX-AD2604 NX-AD2604 NX-AD2604 NX-AD2604 NX-AD2608 NX-AD3603 NX-AD3604 NX-AD4604 NX-AD4604 NX-AD4604 NX-AD4604 NX-AD2203 NX-AD2204 NX-AD3204 NX-AD3204 NX-AD3204 NX-AD4204 NX-AD4204				
			1/8000	-4000 to 4000	±0.2% (full scale)	Differential input	250 μs/point		Free-Run refreshing					
	2 points		1/30000	-15000 to 15000	±0.1% (full scale)	Differential input	10 μs/point	-	Selectable Synchronous I/O refreshing or Free-Run refreshing	NX-AD2608				
Voltage					±0.2%	Single-ended input			Free-Run	NX-AD3603				
		-10 to +10	1/8000	-4000 to 4000	(full scale)	Differential input	250 μs/point	1 MΩ	refreshing	NX-AD3604				
	4 points	V	1/30000	-15000 to 15000	±0.1% (full scale)	Differential input	10 μs/point	min.	Selectable Synchronous I/O refreshing or Free-Run refreshing	NX-AD3608				
8 pc					±0.2%	Single-ended input			Free-Run	NX-AD4603				
			1/8000	-4000 to 4000	±0.2% (full scale)	Differential	250 μs/point		refreshing	NX-AD4604				
	8 points		1/30000	-15000 to 15000	±0.1% (full scale)	Differential	10 μs/point		Selectable Synchronous I/O refreshing or Free-Run refreshing	NX-AD4608				
					±0.2%	Single-ended input			Free-Run	NX-AD2203				
			1/8000	0 to 8000	(full scale)	Differential input	250 μs/point		refreshing	NX-AD2204				
	2 points						1/30000	0 to 30000	±0.1% (full scale)	Differential input	10 μs/point	250 Ω	Selectable Synchronous I/Orefreshing or Free-Run refreshing	NX-AD2208
Current nput type			-	-	-		-	±0.2% Single-ended input		250 32	Free-Run	NX-AD3203		
		4 to	1/8000	0 to 8000	(full scale)	Differential input	250 μs/point		refreshing	NX-AD3204				
	4 points	20 mA	1/30000	0 to 30000	±0.1% (full scale)	Differential input	10 μs/point		Selectable Synchronous I/O refreshing or Free-Run refreshing	NX-AD3208				
		1			±0.2%	Single-ended input			Free-Run	NX-AD4203				
			1/8000	0 to 8000	(full scale)	Differential input	250 μs/point		refreshing	NX-AD4204				
	8 points		1/30000	0 to 30000	±0.1% (full scale)	Differential input	10 μs/point	85 Ω	Selectable Synchronous I/O refreshing or Free-Run refreshing	NX-AD4208				

				Specificatio	on						
Product name	Number of points	Input range	Resolution	Output setting value, decimal number (0 to 100%)	Over all accuracy (25°C)	Conversion time	I/O refreshing method	Model			
			1/8000	-4000 to 4000	±0.3% (full scale)	250 μs/point	Free-Run refreshing	NX-DA2603			
Voltage Output type	2 points	104-101	1/30000	-15000 to 15000	±0.1% (full scale)	10 μs/point	Selectable Synchronous I/O refreshing or Free-Run refreshing	NX-DA2605			
		10 to +10 V	1/8000	-4000 to 4000	±0.3% (full scale)	250 µs/point	Free-Run refreshing	NX-DA3603			
	4 points		1/30000	-4000 to 4000 (full scale) 250 μs/point Free-Run retreshin -15000 to 15000 ±0.1% 10 μs/point Selectable Synchronous I/O	Synchronous I/O refreshing or Free-Run	NX-DA3605					
			1/8000	0 to 8000	±0.3% (full scale)	250 μs/point	Free-Run refreshing	NX-DA2203			
Current Output type	2 points						0 to 30000	±0.1% (full scale)	10 μs/point	Selectable Synchronous I/O refreshing or Free-Run refreshing	NX-DA2205
		– 4 to 20 mA	1/8000	0 to 8000	±0.3% (full scale)	250 μs/point	Free-Run refreshing	NX-DA3203			
	4 points		1/30000	0 to 30000	±0.1% (full scale)	10 μs/point	Selectable Synchronous I/O refreshing or Free-Run refreshing	NX-DA3205			

Analog Output Units

Temperature Control Units/Temperature Input Units/Heater Burnout Detection Units ● Temperature Control Units

Dura durat				Spec	ification				
Product name	Number of channels	Input type	Output	Output capacity	CT Input capacity	Control type	Conversion time	I/O refreshing method	Model
Temperature Control Unit 2Ch type			Voltage output	2 points	2 points	Standard Control			NX-TC2405
	2 Ch		(for driving SSR)	2 points	None	Standard Control			NX-TC2406
	2 011		Voltage output (for driving SSR)	4 points	None	Heating and Cooling Control			NX-TC2407
		Multi-input (Thermocoup le and	Linear current output	2 points	None	Standard Control	50 m sec	Free-Run	NX-TC2408
Temperature Control Unit 4Ch type		Resistance thermometer)	Voltage output	4 points	4 points	Standard Control	50 m sec	refreshing	NX-TC3405
	4 Ch		(for driving SSR)		None	Standard Control			NX-TC3406
	4 011		Voltage output (for driving SSR)	8 points	None	Heating and Cooling Control			NX-TC3407
			Linear current output	4 points	None	Standard Control			NX-TC3408

				Specification				
Product name	Number of points	Input type	Resolution (25°C)	Over all accuracy (25°C)	Conversion time	I/O refreshing method	Terminals	Model
	2 points						16 Terminals	NX-TS2101
hermocouple put type	4 points	_	0.1°C max. *1		250 ms/Unit		16 Terminals x 2	NX-TS3101
-	2 points	Thermocouple	0.01°C max. 1				16 Terminals	NX-TS2102
	4 points			10 ms/Unit		16 Terminals x 2	NX-TS3102	
	2 points		0.001°C max.		60 ms/Unit		16 Terminals	NX-TS2104
	4 points			Refer to your OMRON website		Free-Run	16 Terminals x 2	NX-TS3104
	2 points		0.1°C max.	for details.		refreshing	16 Terminals	NX-TS2201
Resistance Thermometer nput type	4 points	_			250 ms/Unit		16 Terminals x 2	NX-TS3201
	2 points	Resistance					16 Terminals	NX-TS2202
	4 points	 Thermometer (Pt100/Pt1000, three-wire) *2 	0.01°C max.		10 ms/Unit		16 Terminals x 2	NX-TS3202
	2 points	-					16 Terminals	NX-TS2204
	4 points		0.001°C max.		60 ms/Unit		16 Terminals x 2	NX-TS3204

• Temperature Input Units

***1.** The resolution is 0.2°C max. when the input type is R, S, or W. ***2.** The NX-TS2202 and NX-TS3202 only support Pt100 three-wire sensor.

Heater Burnout Detection Units

				Specification				
Product name	CT inpu	ut section		Con	trol output sectio	n		Model
	Number of inputs	Maximum heater current	Number of outputs	Internal I/O common	Maximum load current	Rated voltage	I/O refreshing method	
Heater Burnout Detection Unit	4	50 A AC	4	NPN		12 to 24 VDC	Free-Run	NX-HB3101
	4	50 A AC	4	PNP	Unit	24 VDC	refreshing	NX-HB3201

Optional Products

Product name	Specification	Model
Unit/Terminal Block Coding Pins	Pins for 10 Units (30 terminal block pins and 30 Unit pins)	NX-AUX02

Product name	Specification	Model
Current Transformer (CT)	Hole diameter: 5.8 mm	E54-CT1
	Hole diameter: 5.8 mm	E54-CT1L *
	Hole diameter: 12.0 mm	E54-CT3
	Hole diameter: 12.0 mm	E54-CT3L *

*Lead wires are included with these CTs. If UL certification is required, use these CTs.

Load Cell Input Unit

	Specification						
Product name	Number of points	Conversion cycle	I/O refreshing method *	Load cell excitation voltage	Input range	Model	
Load Cell Input Unit	1	125 μs	 Free-Run refreshing Synchronous I/O refreshing Task period prioritized refreshing 	5 VDC ± 10%	-5.0 to 5.0 mV/V	NX-RS1201	

* Refer to the I/O Refreshing in the NX-series Load Cell Input Unit User's Manual (Cat. No. W565) for detailed information on I/O refresh cycle. Note: The NX-RS1201-K Load Cell Input Unit with the test and calibration certificate is also available. Ask your OMRON representative for details.

Position Interface Units: Incremental Encoder Input Units

		Specification					
Product name	Number of channels	External inputs	Maximum response frequency	I/O refreshing method	Number of I/O entry mappings	Remarks	Model
Incremental	Encoder 1 (PNP) 3	3 (NPN)				24-V voltage input	NX-EC0112
		3 (PNP)	– 500 kHz		1/1		NX-EC0122
input offic		3 (NPN)		 Free-Run refreshing Synchronous I/O refresh- 		Line receiver input	NX-EC0132
	1	3 (PNP)	– 4 MHz				NX-EC0142
3.1	2 (NPN) 2 (PNP) None						NX-EC0212
		None	500 kHz	ing 500 kHz		24-V voltage input	NX-EC0222

Position Interface Units: SSI Input Units

	Specification					
Product name	Number of channels	Input/Output form	Maximum data length	Encoder power supply	Type of external connections	Model
SSI Input Unit	1	EIA standard RS-422-A	32 bits	24 VDC, 0.3 A/CH	Screwless push-in terminal block (12 terminals)	NX-ECS112
	2	EIA standard RS-422-A	32 bits	24 VDC, 0.3 A/CH	Screwless push-in terminal block (12 terminals)	NX-ECS212

Position Interface Units: Pulse Output Units

				Specification	ו			
Product name	Number of channels * 1	External inputs	External outputs	Maximum pulse output speed	I/O refreshing method	Number of I/O entry mappings	Control output interface	Model
	1 (NPN)	2 (NPN)	1 (NPN)				Open	NX-PG0112
Pulse Output Unit	1 (PNP)	2 (PNP)	1 (PNP) 500 kpps		1/1	collector output	NX-PG0122	
		5 inputs/CH (NPN)	3 outputs/CH (NPN)	- 4 Mpps	 Synchronous I/O refreshing 	2/2	Line driver	NX-PG0232-5
		5 inputs/CH (PNP)	3 outputs/CH (PNP)		 Task period pri- oritized refresh- 	2/2		NX-PG0242-5
		5 inputs/CH (NPN)	3 outputs/CH (NPN)		4 Mpps	4 Mpps ing *2	ing *2	4/4
4	5 inputs/CH (PNP)	3 outputs/CH (PNP)	-		4/4		NX-PG0342-5	

*1. This is the number of pulse output channels.
 *2. Unit version 1.2 or later and an NX-ECC203 EtherCAT Coupler Unit are required.

Product name	Specifications	Model	
	Flat Cable Connectors type (Terminal block with M3 screws) 34 terminals		XW2B-34G4
	Flat Cable Connectors type (Terminal block with M3.5 screws) 34 terminals		XW2B-34G5
connector-Terminal Block Conversion Unit	MIL Connectors type (Slim Connector) 34 terminals		XW2D-34G6
Block Conversion Unit	MIL Connectors type (Phillips screw) 34 terminals		XW2R-J34GD-T
	MIL Connectors type (Slotted screw (rise up)) 34 terminals		XW2R-E34GD-T
	MIL Connectors type (Push-in spring) 34 terminals		XW2R-P34GD-T
		Cable length: 0.5 m	XW2Z-050EE
Cable for Connector-Terminal Block Conversion Unit		Cable length: 1 m	XW2Z-100EE
	34-terminal MIL Connector to	Cable length: 1.5 m	XW2Z-150EE
	34-terminal MIL Connector	Cable length: 2 m	XW2Z-200EE
		Cable length: 3 m	XW2Z-300EE
		Cable length: 5 m	XW2Z-500EE

Cables and Connectors for Line Driver Output Units with MIL Connectors

Note: Each of NX-PG0232-5 and NX-PG0242-5 has one MIL connector. Therefore, one Connector-Terminal Block Conversion Unit is required. Each of NX-PG0332-5 and NX-PG0342-5 has two MIL connectors. Therefore, two Connector-Terminal Block Conversion Units are required.

Communications Interface Units

Product name	Serial interface	External connection terminals	Number of serial ports	Communications function	Model
Communications Interface Unit	RS-232C	Screwless clamping			NX-CIF101
	RS-422A/485	terminal block	1 port	 No-protocol serial communications Serial line monitor 	NX-CIF105
	RS-232C	D-Sub connector	2 ports		NX-CIF210

RFID Units

Amplifier/Antenna	No. of unit numbers used	Model
V680 series		
	1	NX-V680C1
	2	NX-V680C2
3		0 series

IO-Link Master Unit

Product name	Number of IO-Link ports	I/O refreshing method	I/O connection terminals	Model
IO-Link Master Unit				
	4	Free-Run refreshing	Screwless clamping terminal block	NX-ILM400

Note: For details of IO-Link sensors and sensor I/O connectors, refer to the IO-Link Series Catalog (Cat. No. Y229).

System Units

Product Name	Specifications	Model
Additional NX Unit Power Supply Unit	Power supply voltage: 24 VDC (20.4 to 28.8 VDC) NX Bus power supply capacity: 10 W max.	NX-PD1000
Additional I/O Power Supply Unit	Power supply voltage: 5 to 24 VDC (4.5 to 28.8 VDC) I/O power feed maximum current: 4 A	NX-PF0630
	Power supply voltage: 5 to 24 VDC (4.5 to 28.8 VDC) I/O power feed maximum current: 10 A	NX-PF0730
I/O Power Supply Connection Unit	Number of I/O power terminals: IOG: 16 terminals Current capacity of I/O power terminal: 4 A/terminal max.	NX-PC0010
	Number of I/O power terminals: IOV: 16 terminals Current capacity of I/O power terminal: 4 A/terminal max.	NX-PC0020
	Number of I/O power terminals: IOV: 8 terminals, IOG: 8 terminals Current capacity of I/O power terminal: 4 A/terminal max	NX-PC0030
Shield Connection Unit	Number of shield terminals: 14 terminals (The lower two terminals are functional ground terminals.)	NX-TBX01

Optional Products and Maintenance Products

Product name	Specification	Model
Unit/Terminal Block Coding Pins	For 10 Units (Terminal Block: 30 pins, Unit: 30 pins)	NX-AUX02
End Cover	One End Cover is provided as a standard accessory with the Communication Coupler Unit.	NX-END01
DIN Track Insulation Spacer	A Spacer to insulate the control panel from the DIN Track. To insulate the Slave Terminal from the control panel, use Din Track Insulation Spacers.	NX-AUX01

Product name	No. of terminals Terminal number indications Ground terminal mark Terminal current capacity		Model		
	8	A/B			NX-TBA082
	12	A/B		10 A	NX-TBA122
	16	A/B	None		NX-TBA162
Terminal Block	12	C/D			NX-TBB122
	16	C/D			NX-TBB162
	8	A/B	Provided	1	NX-TBC082
	16	A/B	FIONIded		NX-TBC162

Safety Control Units NX Series

Ordering Information

Safety CPU Units

		Specification							
Unit type	Appearance	Maximum number of safety I/O points	Program capacity	Number of safety master connections	I/O refreshing method	Unit version	Model		
Safety CPU		256 points	512 KB	32	Free-Run refreshing	Ver.1.1	NX-SL3300		
Unit		1024 points	2048 KB	128	Free-Run refreshing	Ver.1.1	NX-SL3500		

Note: Connect the Safety CPU Unit to the NX1P2 CPU Unit via the EtherCAT Coupler Unit.

Safety Input Units

		Specification								
Unit type	Appearance	Number of safety input points	Number of test output points	Internal I/O common	Rated input voltage	OMRON special safety input devices	Number of safety slave connections	I/O refreshing method	Unit version	Model
Safety Input		4 points	2 points	Sinking inputs (PNP)	24 VDC	Can be connected.	1	Free-Run refreshing	Ver.1.1	NX-SIH400
Unit	I	8 points	2 points	Sinking inputs (PNP)	24 VDC	Cannot be connected.	1	Free-Run refreshing	Ver.1.0	NX-SID800

Note: Connect the Safety Input Unit to the NX1P2 CPU Unit via the EtherCAT Coupler Unit.

Safety Output Units

		Specification							
Unit type	Appearance	Number of safety output points	Internal I/O common	Maximum load current	Rated voltage	Number of safety slave connections	I/O refreshing method	Unit version	Model
Safety Output Unit		2 points	Sourcing outputs (PNP)	2.0 A/point, 4.0 A/Unit at 40°C, and 2.5 A/Unit at 55°C The maximum load current depends on the installation orientation and ambient temperature.	24 VDC	1	Free-Run refreshing	Ver.1.0	NX-SOH200
		4 points	Sourcing outputs (PNP)	0.5 A/point and 2.0 A/Unit	24 VDC	1	Free-Run refreshing	Ver.1.0	NX-SOD400

Note: Connect the Safety Output Unit to the NX1P2 CPU Unit via the EtherCAT Coupler Unit.

Product Name	Specification						
Unit/Terminal Block Coding Pins	For 10 Units (Terminal Block: 30 pins, U	r 10 Units erminal Block: 30 pins, Unit: 30 pins)					
	Specification						
Product name	No. of terminals	Terminal number indications	Ground terminal mark	Terminal current capacity	Model		
	8	A/B	None	10 A	NX-TBA082		
Terminal Block	16	A/B	None	10 A	NX-TBA162		

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